



UNIVERSITY OF WATERLOO  
FACULTY OF ENGINEERING  
Department of Electrical &  
Computer Engineering

ECE 204 *Numerical methods*

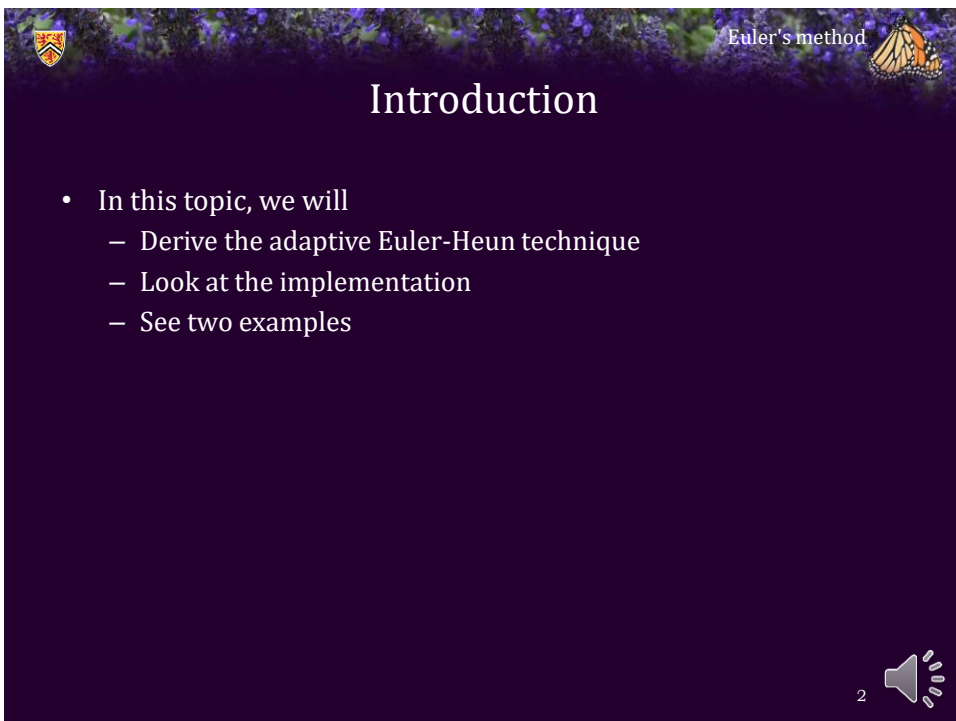
# The adaptive Euler-Heun method

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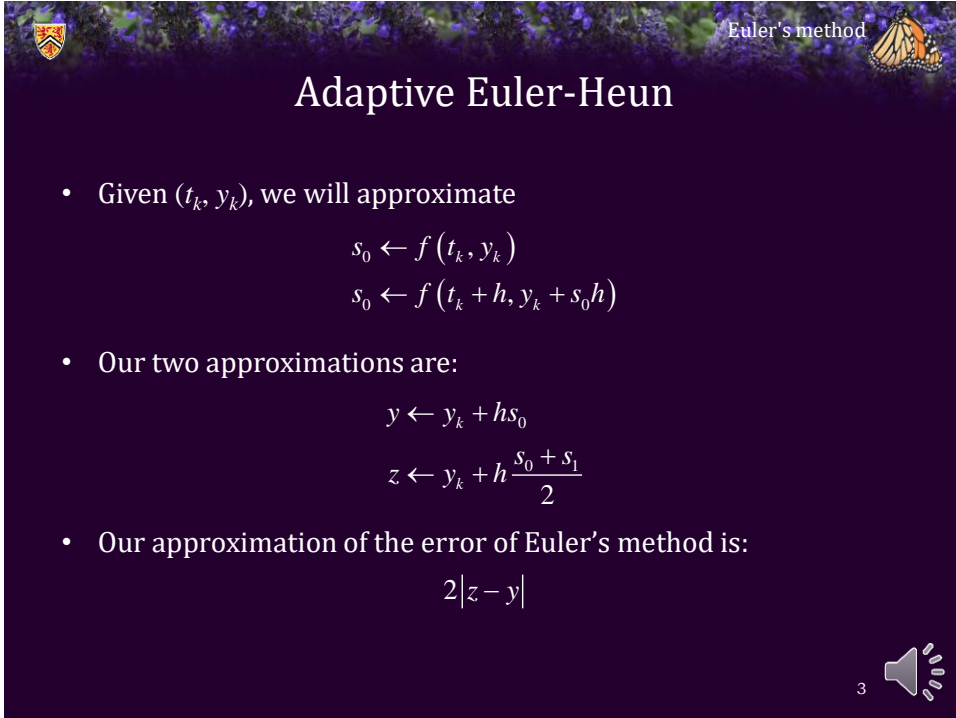
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# Introduction

- In this topic, we will
  - Derive the adaptive Euler-Heun technique
  - Look at the implementation
  - See two examples



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## Adaptive Euler-Heun

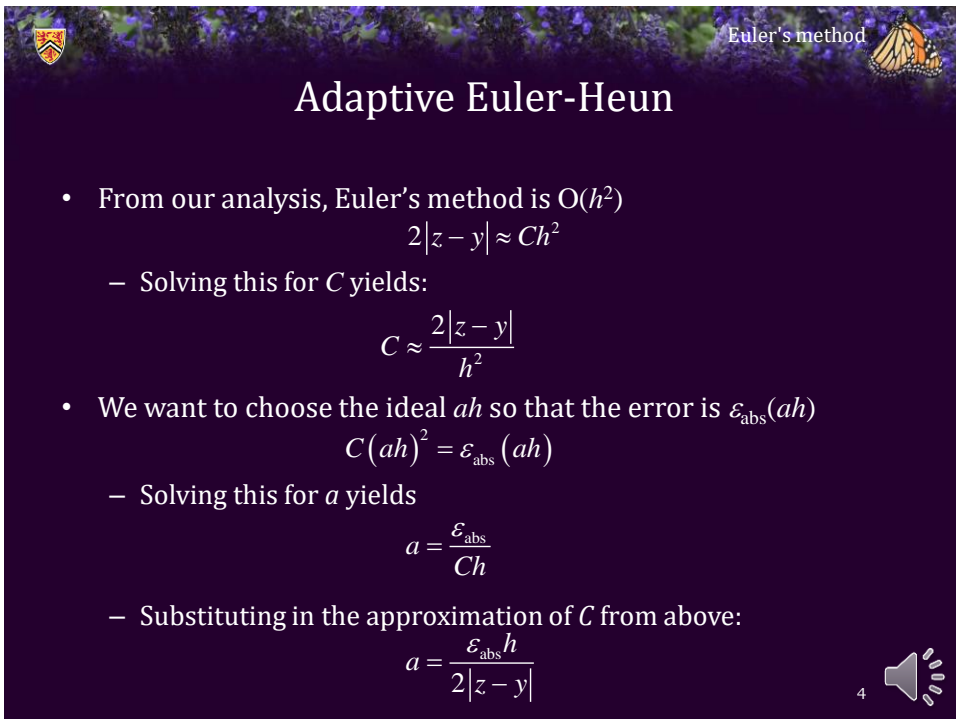
- Given  $(t_k, y_k)$ , we will approximate
 
$$s_0 \leftarrow f(t_k, y_k)$$

$$s_1 \leftarrow f(t_k + h, y_k + s_0 h)$$
- Our two approximations are:
 
$$y \leftarrow y_k + h s_0$$

$$z \leftarrow y_k + h \frac{s_0 + s_1}{2}$$
- Our approximation of the error of Euler's method is:
 
$$2|z - y|$$

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## Adaptive Euler-Heun



- From our analysis, Euler's method is  $O(h^2)$ 

$$2|z - y| \approx Ch^2$$
  - Solving this for  $C$  yields:
 
$$C \approx \frac{2|z - y|}{h^2}$$
- We want to choose the ideal  $ah$  so that the error is  $\varepsilon_{\text{abs}}(ah)$ 

$$C(ah)^2 = \varepsilon_{\text{abs}}(ah)$$
  - Solving this for  $a$  yields
 
$$a = \frac{\varepsilon_{\text{abs}}}{Ch}$$
  - Substituting in the approximation of  $C$  from above:
 
$$a = \frac{\varepsilon_{\text{abs}} h}{2|z - y|}$$

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## Adaptive Euler-Heun

- Issue:
  - If we are always aiming for the *ideal* step size, the next *ideal* step size may be slightly larger or smaller
  - If we use too large a step size, we will be forced to recalculate
    - Therefore, we will actually use  $0.9ah$

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## Implementation


- The implementation is straight-forward:
 

```
do {
    double s0{ qdy.back() };
    double y{ qy.back() + h*s0 };
    double s1{ f( qt.back() + h, y ) };
    double z{ qy.back() + h*(s0 + s1)/2.0 };


    double a{ eps_abs*h/(2.0*std::abs( z - y ) ) };

    if ( ( a > 1.0 ) || ( h == h_rng.first ) ) {
        qt.push( qt.back() + h );
        qy.push( z );
        qdy.push( f( qt.back(), z ) );
        found = true;
    }

    a *= 0.9;
}
```

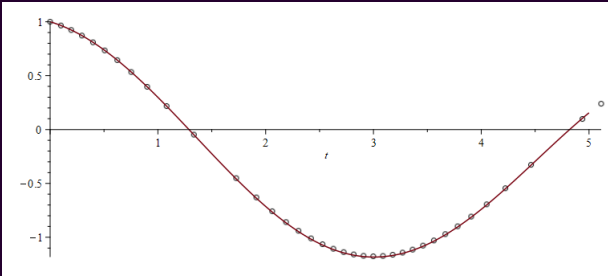
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## Example

- Suppose we have  $y^{(1)}(t) = -0.2y(t) - \sin(t) - 0.1$   
 $y(0) = 1$ 
  - With  $h_{\min} = 0.01$ ,  $h_{\max} = 1$  and  $\varepsilon_{\text{abs}} = 0.1$ , we have



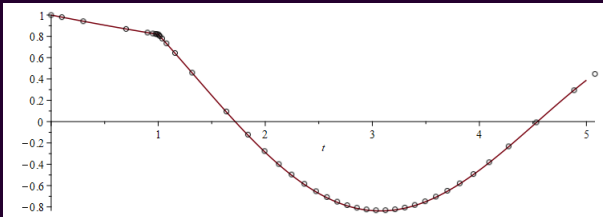
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## Example

- Suppose we have  $y^{(1)}(t) = -0.2y(t) - \begin{cases} 0 & t < 1 \\ \sin(t) - 0.1 & t \geq 1 \end{cases}$   
 $y(0) = 1$ 
  - With  $h_{\min} = 0.01$ ,  $h_{\max} = 1$  and  $\varepsilon_{\text{abs}} = 0.1$ , we have



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## Summary

- Following this topic, you now
  - Understand the adaptive Euler-Heun method
  - Are aware of the derivation
  - Have seen the implementation
  - Have seen two examples



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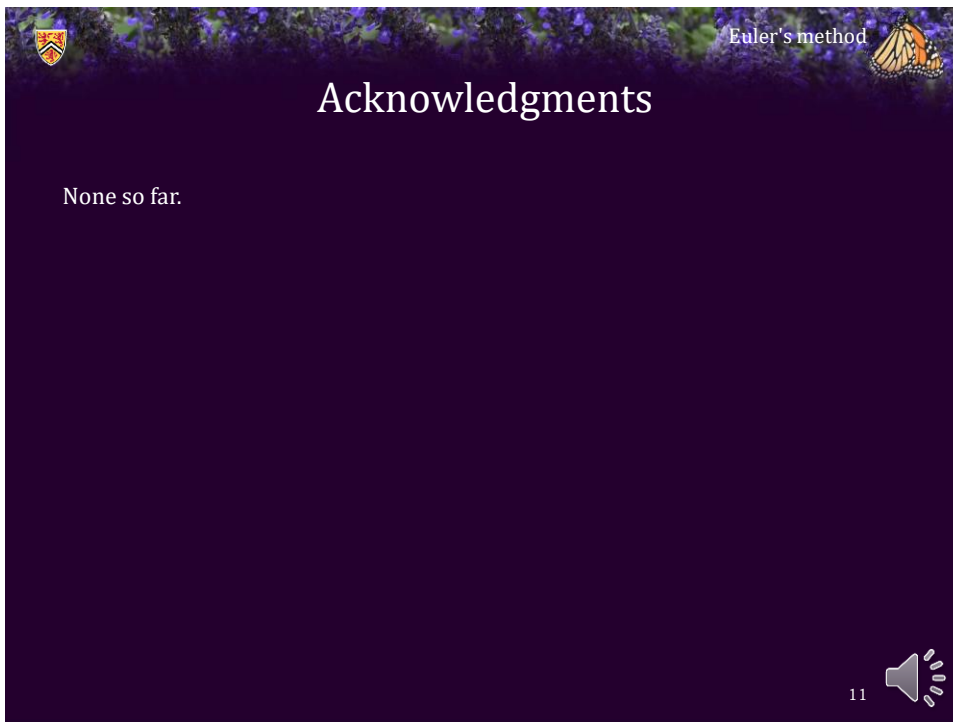
## References

- [1] [https://en.wikipedia.org/wiki/Euler\\_method](https://en.wikipedia.org/wiki/Euler_method)
- [2] [https://en.wikipedia.org/wiki/Heun%27s\\_method](https://en.wikipedia.org/wiki/Heun%27s_method)
- [3] [https://en.wikipedia.org/wiki/Adaptive\\_algorithm](https://en.wikipedia.org/wiki/Adaptive_algorithm)
- [4] [https://en.wikipedia.org/wiki/Adaptive\\_step\\_size](https://en.wikipedia.org/wiki/Adaptive_step_size)




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# Acknowledgments

None so far.


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# Colophon

These slides were prepared using the Cambria typeface. Mathematical equations use Times New Roman, and source code is presented using Consolas. Mathematical equations are prepared in MathType by Design Science, Inc. Examples may be formulated and checked using Maple by Maplesoft, Inc.


The photographs of flowers and a monarch butter appearing on the title slide and accenting the top of each other slide were taken at the Royal Botanical Gardens in October of 2017 by Douglas Wilhelm Harder. Please see

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for more information.

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